



De-noising on the Body Centered Cubic (BCC) Sampling Lattice

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Motivation

- Why is BCC superior to Cartesian (CC) in medical imaging?
 - 3D: saves 30% samples
 - 3D time-varying: saves 50% samples
 - Higher dimensions: potentially higher savings
- BCC grid seems well-positioned to take over the CC grid in medical imaging



Motivation

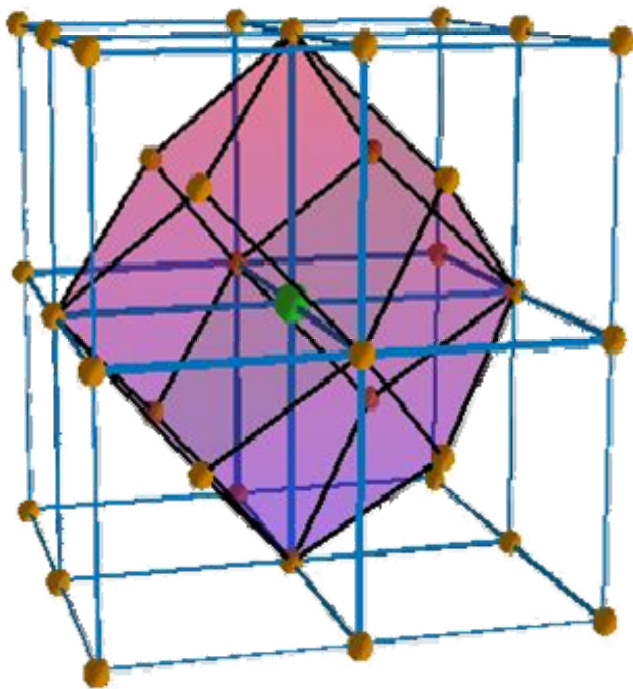
- Why is BCC not used in medical imaging?
 - Few tools for the BCC grid exist
- Why de-noising on the BCC lattice?
 - De-noising is necessary in medical imaging
 - De-noising tools for BCC does not exist
- Ideal goal: BCC is no worse than CC in de-noising



Abstract

- Two types of noise investigated
 - Salt & pepper noise: impulse noise
 - Gaussian white noise: random noise
- Two filters investigated
 - Median filter: salt & pepper noise
 - Gaussian smoothing filter: white noise
- Error plots of CC vs BCC de-noising

The BCC Lattice



- Start with canonical CC lattice
- A lattice point belongs to the BCC lattice if and only if all three of its coordinates are even, or if all three are odd



Sampling Equivalence

■ Theorem

- Consider an unknown 3D signal. On average, to capture the same amount of information via sampling, it takes the BCC lattice roughly 70% of the number of samples that it would take the CC lattice
- In the limit, the exact percentage is $1/\sqrt{2}$
 $\approx 70.7\%$



Stage 1: Sampler

- Marschner Lobb (ML) dataset
- CC: 64 x 64 x 64 samples
- BCC: 45 x 45 x 90 samples
- The number of samples in BCC dataset is roughly 70% of that of CC dataset
- By theorem, they capture roughly the same amount of information from ML



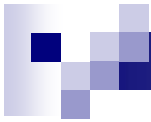
Stage 1: Sampler

- CC/BCC pair: noise free
- CC/BCC pair: salt & pepper noise
 - Input: probability of noise
- CC/BCC pair: Gaussian noise
 - Input: standard deviation = average difference of noise samples



Salt & Pepper Noise Generation

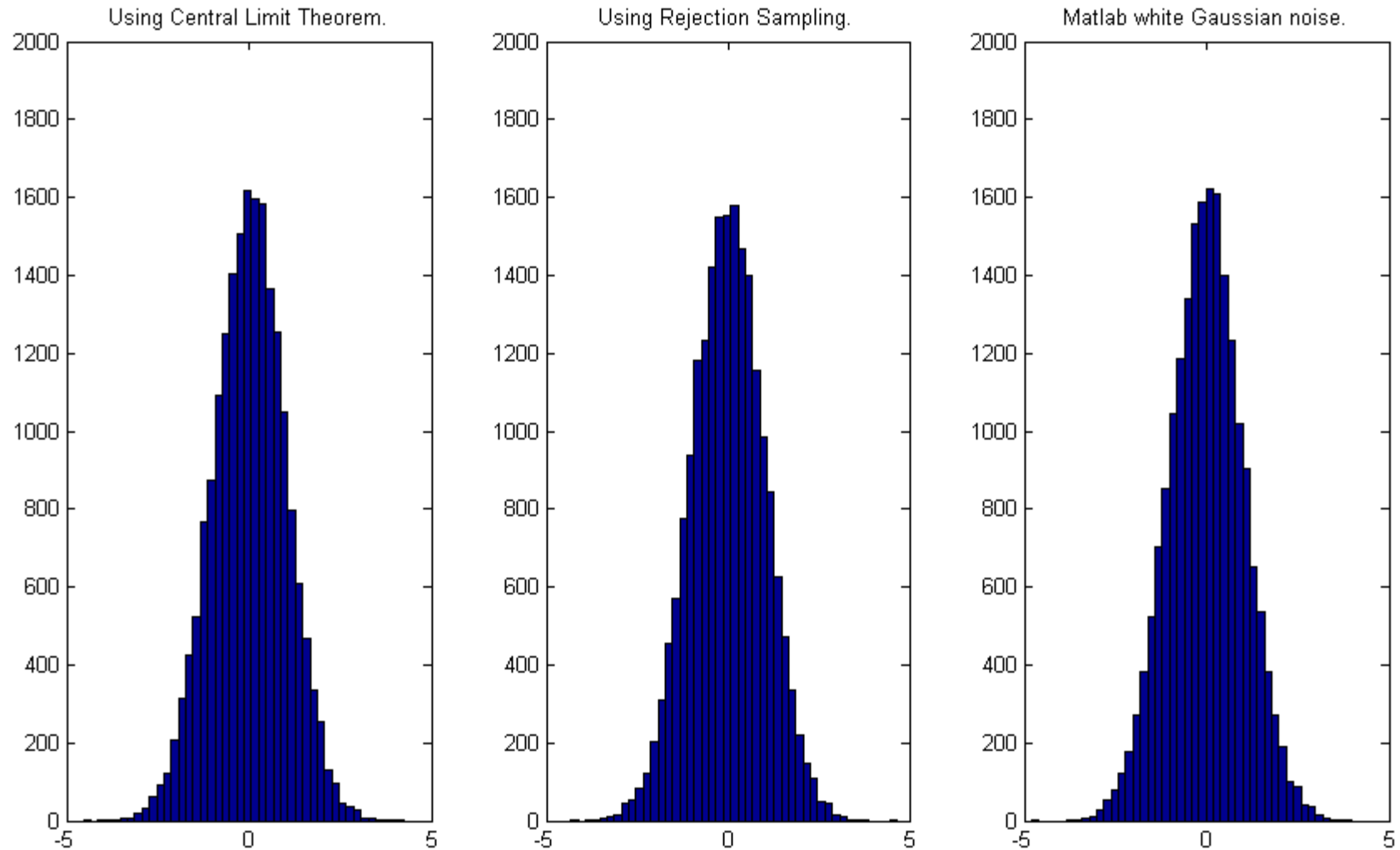
- Input: probability p
- For each sample, generate $y = \text{rand}[0..1]$
 - If $0 \leq y < p/2$, set sample to 0 (pepper)
 - If $p/2 \leq y \leq p$, set sample to 254 (salt)
 - Else leave sample alone



White Noise Generation

- Method 1: The Central Limit Theorem states that the sum of N random numbers will approach normal distribution as N approaches infinity; $N \geq 30$ works
- Method 2: Rejection sampling; dart throwing till a sample falls under the Gaussian envelope; very slow

White Noise Generation





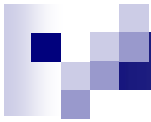
Stage 1: De-noiser

- Input: filter radius, noise type, grid type
- Noise type, grid type -> choose filter
 - Set that filter to the input filter radius
 - Apply the filter to the dataset

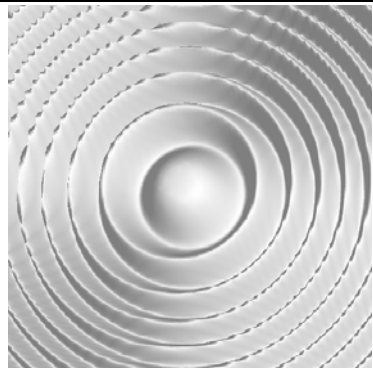
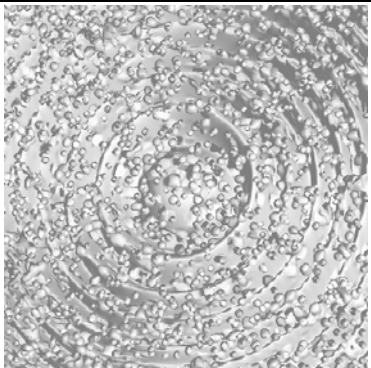
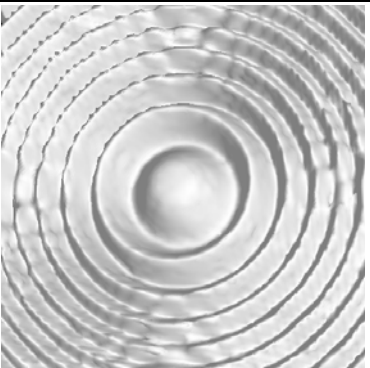
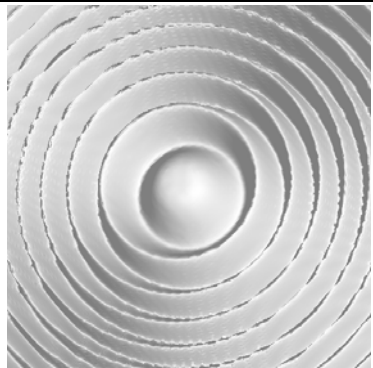
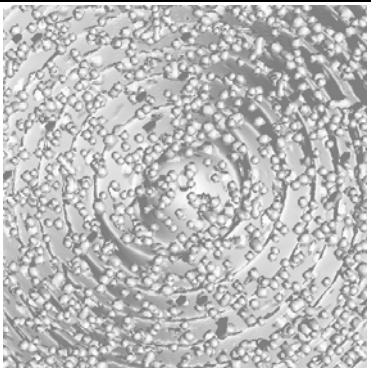
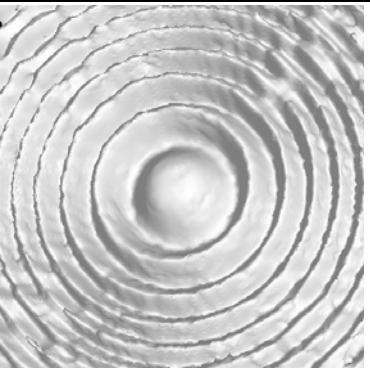


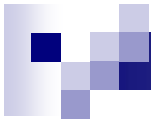
Stage 1: De-noiser

- Four filters to choose from:
 - ☐ CC median filter
 - ☐ BCC median filter
 - ☐ CC Gaussian filter
 - ☐ BCC Gaussian filter

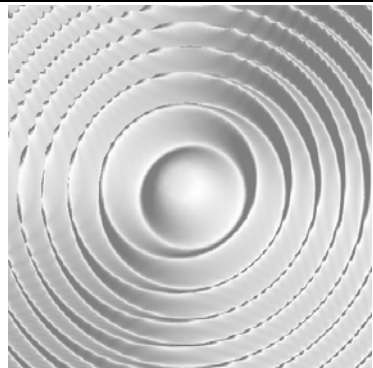
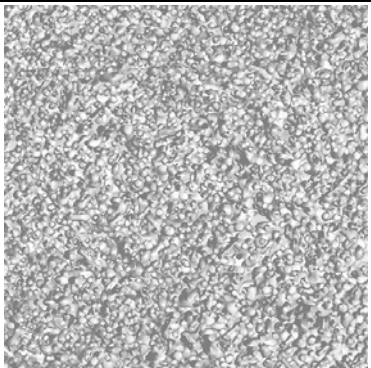
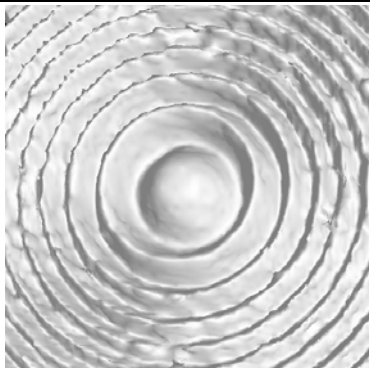
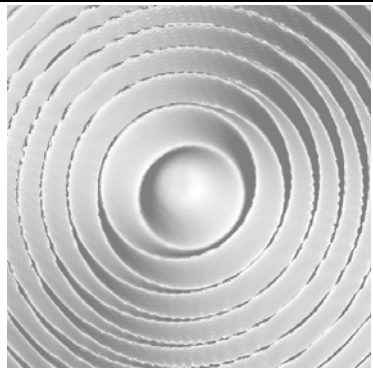
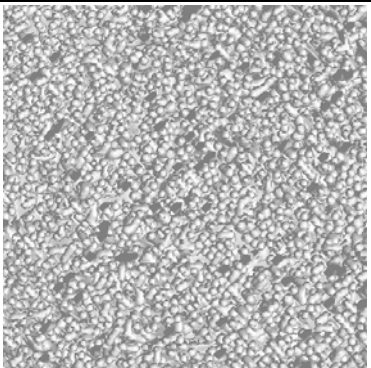
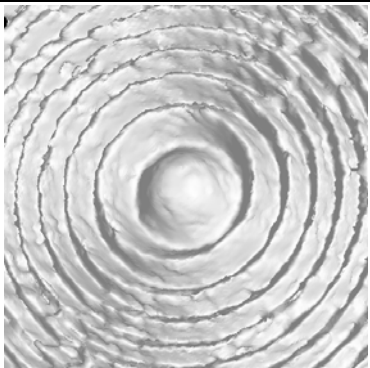


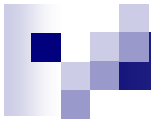
Salt & Pepper: Low Noise

CC Original	CC Salt & Pepper 3%	Filter size = 1.414214 Neighborhood size = 19
		
BCC Original	BCC Salt & Pepper 3%	Filter size = 1.415730 Neighborhood size = 15
		

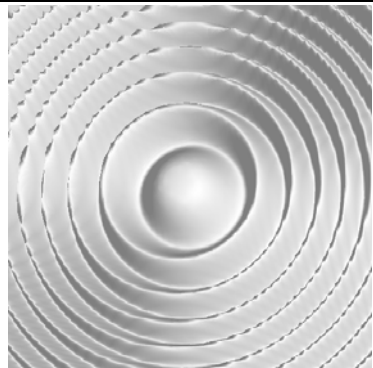
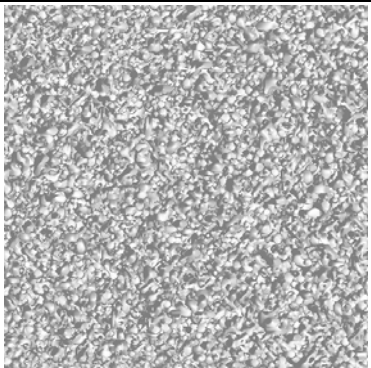
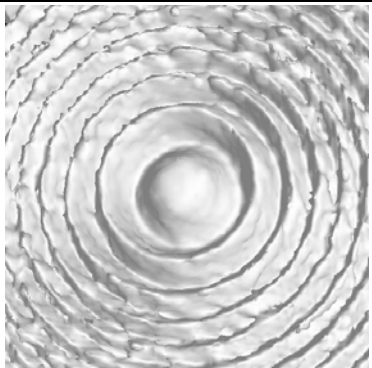
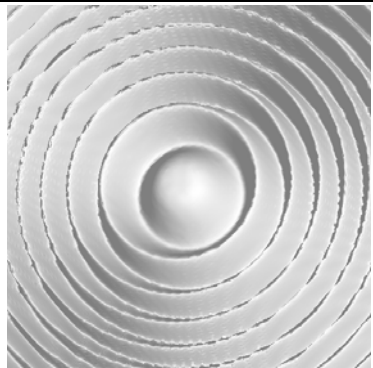
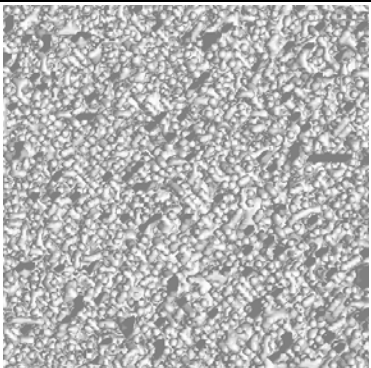
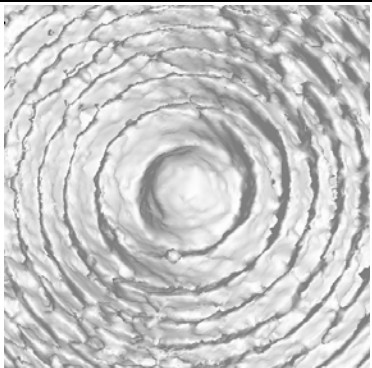


Salt & Pepper: Medium Noise

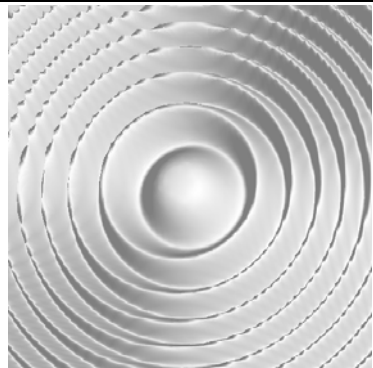
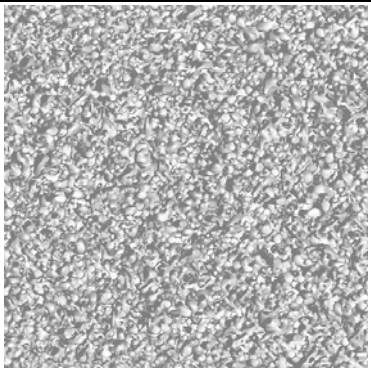
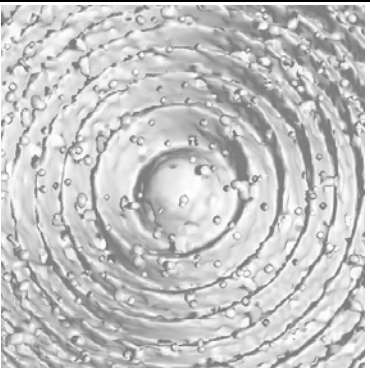
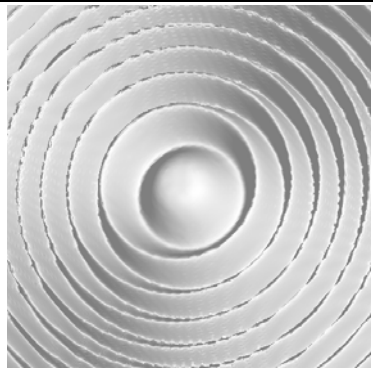
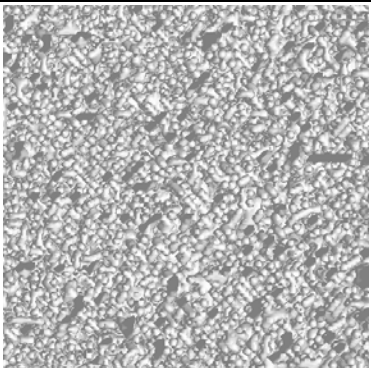
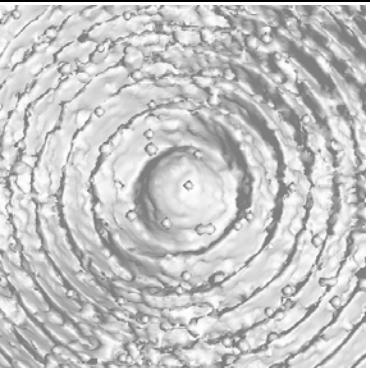
CC Original	CC Salt & Pepper 10%	Filter size = 1.414214 Neighborhood size = 19
		
BCC Original	BCC Salt & Pepper 10%	Filter size = 1.415730 Neighborhood size = 15
		

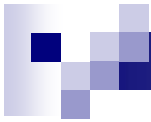


Salt & Pepper: High Noise

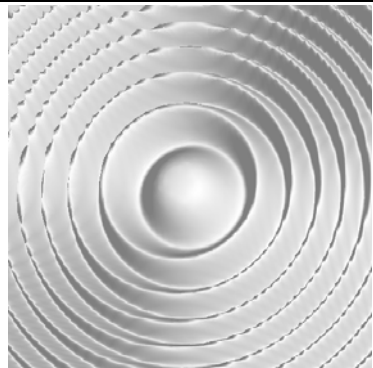
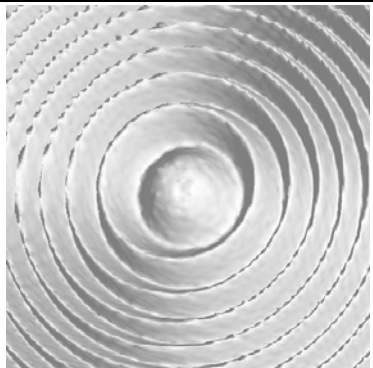
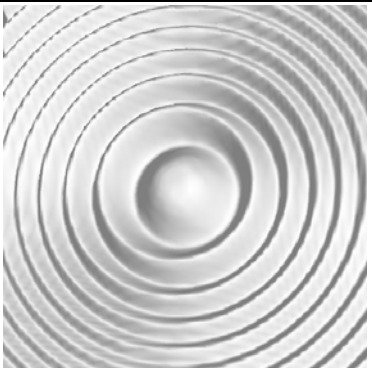
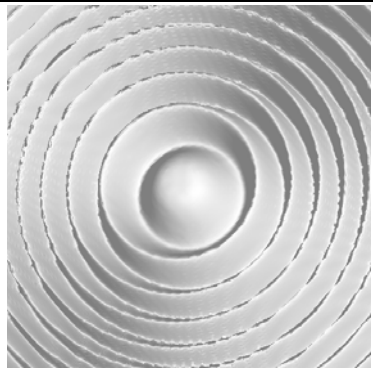
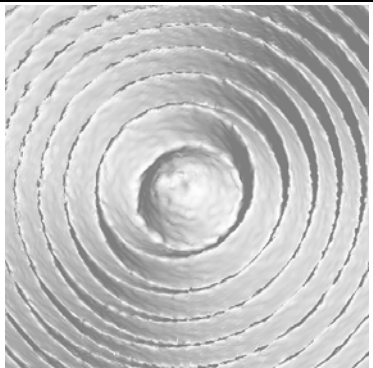
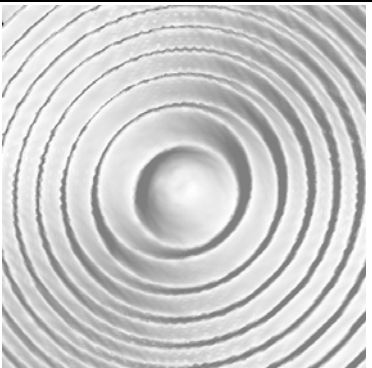
CC Original	CC Salt & Pepper 20%	Filter size = 1.414214 Neighborhood size = 19
		
BCC Original	BCC Salt & Pepper 20%	Filter size = 1.415730 Neighborhood size = 15
		

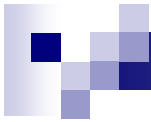
Salt & Pepper: High Noise

CC Original	CC Salt & Pepper 20%	Filter size = 1 Neighborhood size = 7
		
BCC Original	BCC Salt & Pepper 20%	Filter size = 1.226058 Neighborhood size = 9
		

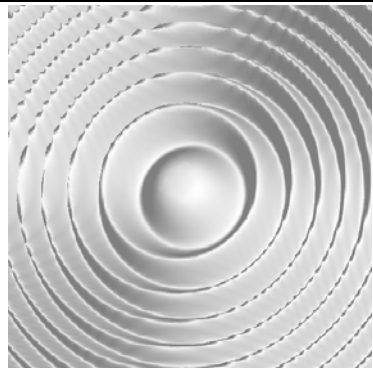
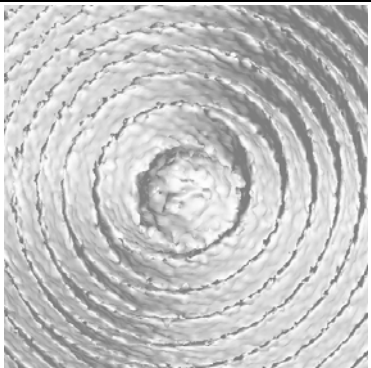
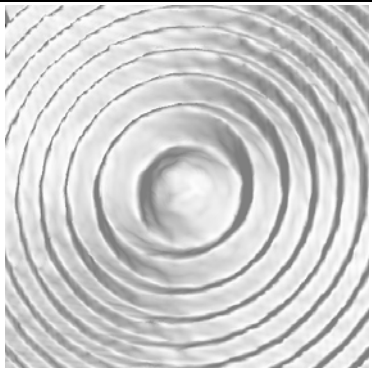
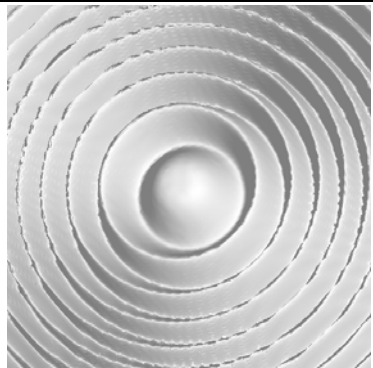
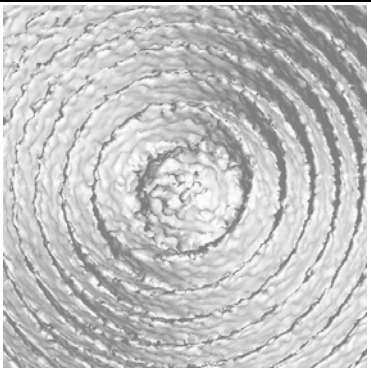
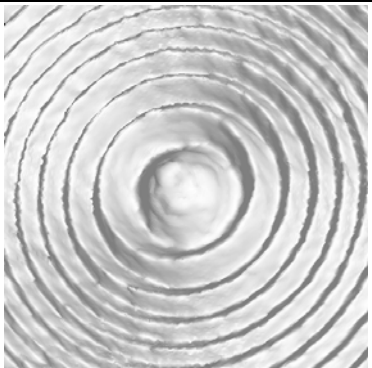


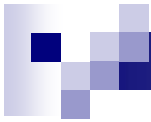
White Noise: Low Noise

CC Original	CC Gaussian Sigma = 2	Filter size = 2.236068 Neighborhood size = 57
		
BCC Original	BCC Gaussian Sigma = 2	Filter size = 2.347723 Neighborhood size = 51
		

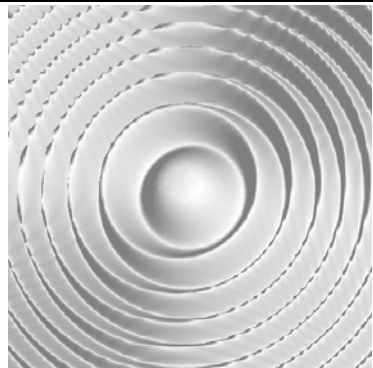
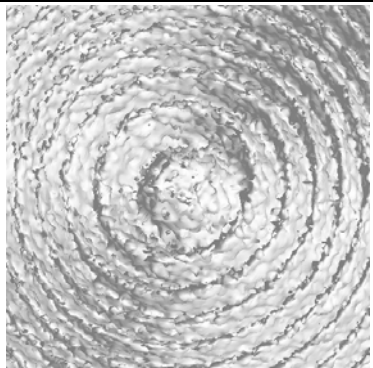
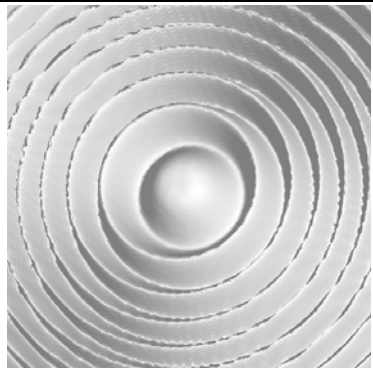


White Noise: Medium Noise

CC Original	CC Gaussian Sigma = 7	Filter size = 2.236068 Neighborhood size = 57
		
BCC Original	BCC Gaussian Sigma = 7	Filter size = 2.347723 Neighborhood size = 51
		



White Noise: High Noise

CC Original	CC Gaussian Sigma = 14	Filter size = 2.236068 Neighborhood size = 57
		
BCC Original	BCC Gaussian Sigma = 14	Filter size = 2.347723 Neighborhood size = 51
		



Stage 2: Data Plot

- Error metric after de-noise:
 - Compute difference between de-noised dataset and noise-free dataset
 - Mean ≈ 0 , so can be ignored
 - Use standard deviation as error metric

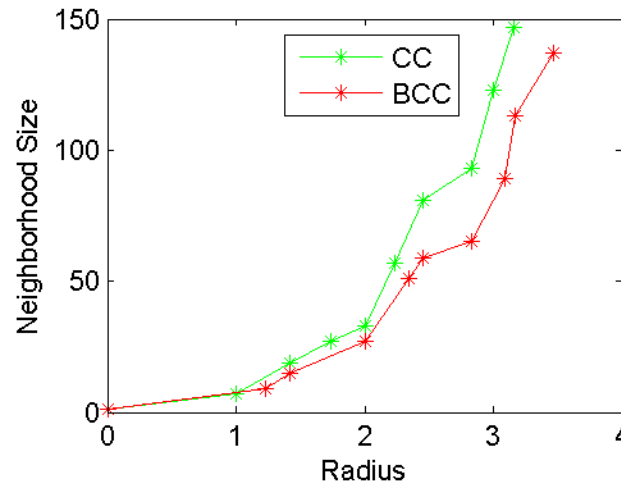
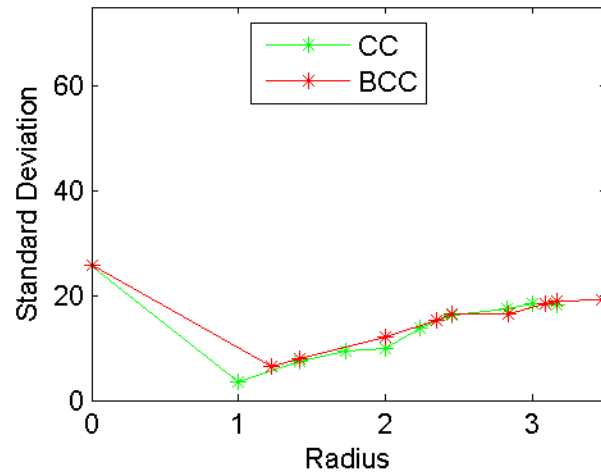


Stage 2: Data Plot

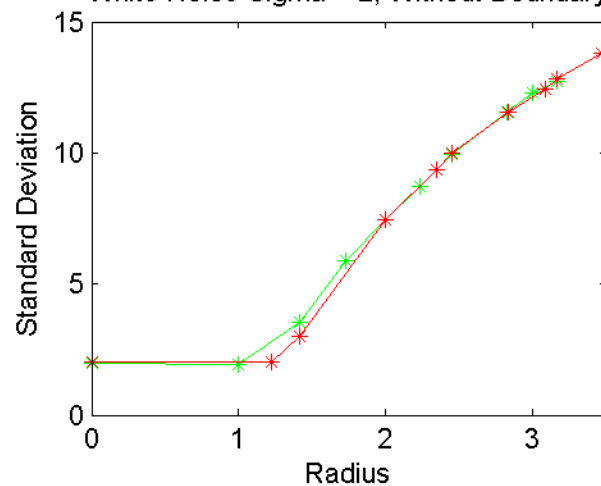
- One 2D point for each neighbourhood
 - Filter radius corresponding to neighbourhood
 - Error after filtering with this radius
- Generate 10 points for first 10 neighbourhoods
 - Can already see a convergent behaviour
 - Larger neighbourhood => slower filtering

Plot: Low Noise

3% Salt & Pepper Noise, Without Boundary



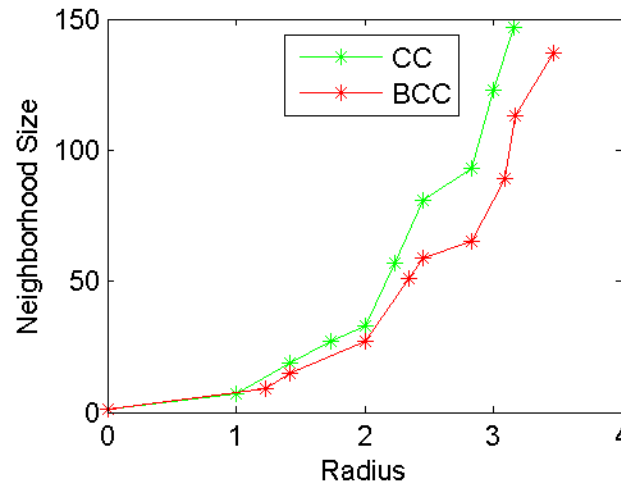
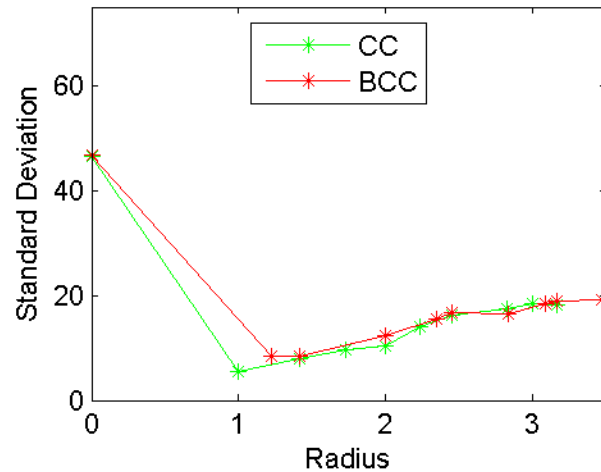
White Noise Sigma = 2, Without Boundary



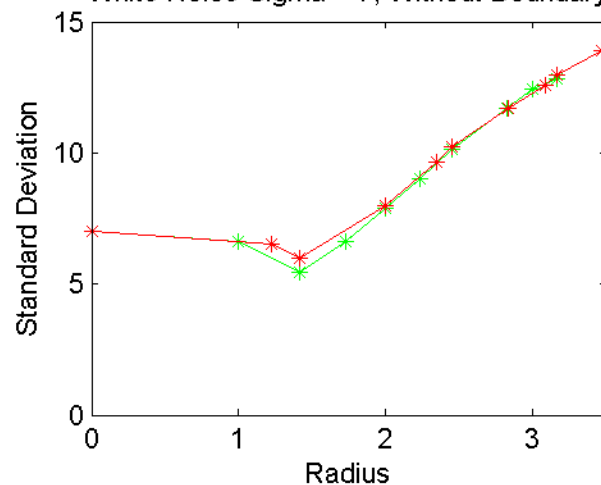
Index	CC Radius	CC Size	BCC Radius	BCC Size
1	0.000000	1	0.000000	1
2	1.000000	7	1.226058	9
3	1.414214	19	1.415730	15
4	1.732051	27	2.002145	27
5	2.000000	33	2.347723	51
6	2.236068	57	2.452117	59
7	2.449490	81	2.831461	65
8	2.828427	93	3.085513	89
9	3.000000	123	3.165669	113
10	3.162278	147	3.467817	137

Plot: Medium Noise

10% Salt & Pepper Noise, Without Boundary



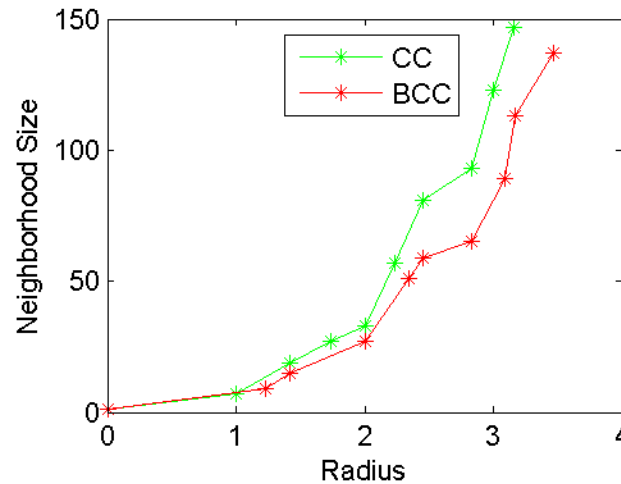
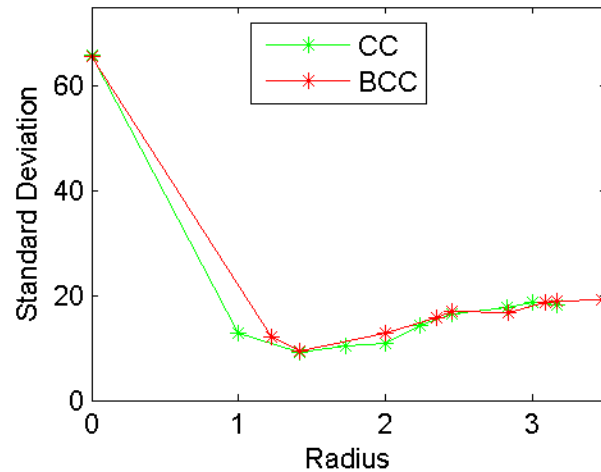
White Noise Sigma = 7, Without Boundary



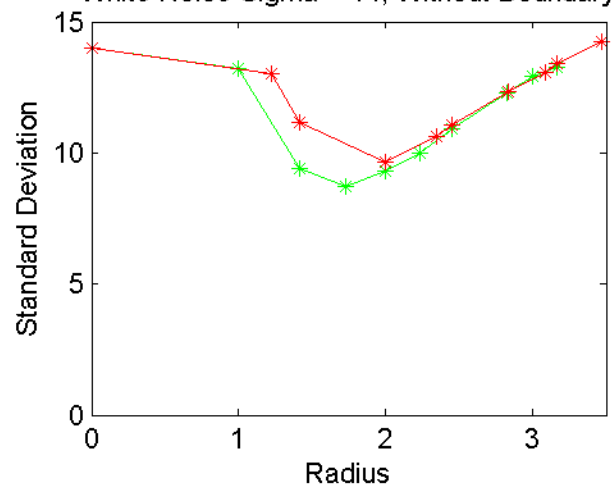
Index	CC Radius	CC Size	BCC Radius	BCC Size
1	0.000000	1	0.000000	1
2	1.000000	7	1.226058	9
3	1.414214	19	1.415730	15
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5	2.000000	33	2.347723	51
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8	2.828427	93	3.085513	89
9	3.000000	123	3.165669	113
10	3.162278	147	3.467817	137

Plot: High Noise

20% Salt & Pepper Noise, Without Boundary



White Noise Sigma = 14, Without Boundary



Index	CC Radius	CC Size	BCC Radius	BCC Size
1	0.000000	1	0.000000	1
2	1.000000	7	1.226058	9
3	1.414214	19	1.415730	15
4	1.732051	27	2.002145	27
5	2.000000	33	2.347723	51
6	2.236068	57	2.452117	59
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10	3.162278	147	3.467817	137



Conclusion

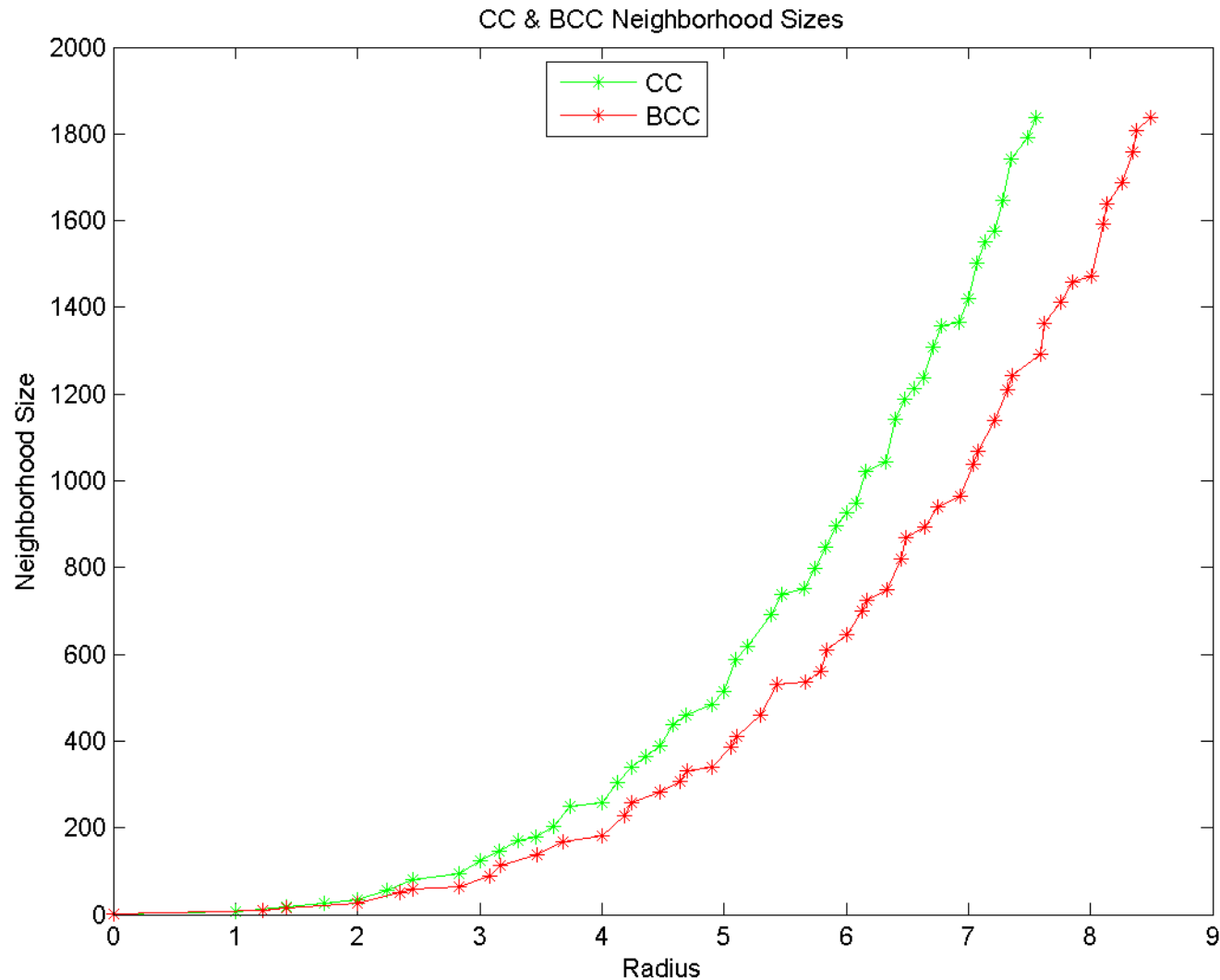
- Median filtering
 - BCC seems comparable to CC
- Gaussian filtering
 - BCC seems better for low noise levels
 - CC seems better for higher noise levels
 - Need further investigation



Bonus: Neighborhood Plot

- Investigate the claim that the ratio of BCC over CC neighbourhood sizes converge to roughly 0.7 (i.e. $1/\sqrt{2}$)
- Plotted first 50 BCC/CC ratios
 - Can see convergent behaviour
 - Know that in the limit, ratio = $1/\sqrt{2}$

Bonus: Neighborhood Plot





References

- Robert Fisher, Simon Perkins, Ashley Walker and Erik Wolfart. [Digital Filters](#). Department of Artificial Intelligence, University of Edinburgh, UK, 2003.
- Complete list:
 - http://www.taimeng.com/grad_school/CMPT775_proj/references.htm

Thank You!

